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Waveguide

I. Area of application

- 10 The invention regards position sensors, in particular their detector unit, based on the principle of travel time measurement of mechanical-elastic impulses in a waveguide, which besides this waveguide, comprises a relatively maneuverable position element, which generates or detects the mechanical-elastic wave.

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II. Technical background

- The waveguide normally consists of a tube, a wire or a ribbon, and can also serve as an electrical conductor. The waveguide can also be arranged in a form-giving, linear or circular body made of non-magnetic material, i.e. plastic or metal, for the
20 seating and suspension of the waveguide.

- Based on the Wiedemann effect, an electric current fed into the waveguide at its superimposition with an external magnetic field oriented laterally to the magnetostrictive waveguide, which originates from a position element, in particular
25 a position magnet, generates a torsion impulse of a mechanical-elastic wave, which spreads out from the place of origin at approx. 2,500 m/s – 6,000 m/s, or the position of the position element, for example, along the waveguide in both directions.

- 30 At a position, usually at one end of the waveguide, the torsion of this mechanical-elastic impulse is detected by a detector unit that is mainly in a fixed position in regards to that of the waveguide. The length of time between the release of the

energizing current and the receipt of the mechanical impulse is thereby a measure of the distance of the movable position element, for example, from the position magnets by the detector mechanism or also the coil or the electromagnets.

5 A typical such sensor is described in US patent 896 714.

The main focus of the invention at hand is on the detector mechanism. This includes a detector coil, which is either arranged around the waveguide or is arranged around a Villary band as a so-called Villary detector, which reaches out
 10 diagonally, in particular, at a 90° angle, from the waveguide and is connected with it in such a manner, in particular, mechanically affixed, i.e. welded, that the torsion impulse running along the waveguide is transformed into a longitudinal wave in the Villary band. Such a longitudinal wave elastically compresses or elongates the Villary band in the crystalline spectrum, and therefore changes its permeability μ .
 15 For this purpose, the Villary band is made of a material with the highest possible magnetic permeability $\Delta\mu_r$, i.e. from nickel or a nickel alloy.

The one magnetoelastic element, i.e. the density wave passing through the Villary band, thus manifests itself in a voltage fluctuation ΔU , which can be tapped as a
 20 information signal at the detector coil.

As is apparent, the larger the information signal ΔU , the larger the change of the magnetic permeability $\Delta\mu_r$ precipitated.

25 In addition, such range of the curve $\Delta\mu_r(H)$ is desired as the operating point or operating range, or the magnetic permeability plotted over the magnetic field strength, in which the magnetic permeability $\Delta\mu_r$ is as linear as possible, relative to the cause but changed as strongly as possible, which is why the function $\Delta\mu_r(H)$ should be developed as steeply as possible in the leading edge and why the
 30 operating range should be established in the approaching linear range.

In the state of the art, a so-called bias magnet in the form of a permanent magnet in the spatial proximity to the detector coil will be arranged for the adjustment of the operating point, i.e. parallel to the Villary band.

- 5 The operating point of the magneto-elastic detector unit is mainly dependent on its position relative to the detector coil near the magnetic parameters of the bias magnets.

10 In many regards, this is detrimental, for example during deployment of the position sensor in locations that are subject to mechanical and in particular, dynamically mechanical stresses and strains or even accelerate thermal impacts, which change the magnetic parameters of the bias magnets and in particular its aging process, which likewise have a change of the magnetic parameters as a consequence.

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In addition, all deviations from the target form arising in the manufacture of the bias magnets are detrimental in the same manner. The same applies for the production-required variation of the magnetic parameters in the manufacture of the bias magnets.

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An additional disadvantage is that the operational point is negatively changed if the position magnets approach the detector coil too closely. According to the state of the art for detector orientation, the waveguide would therefore have to be extended enough over the measurement range, within which the position magnet
25 could move back and forth, that the detector unit with the detector coil was sufficiently far enough away from the measurement range, in order to reduce electromagnetic interferences to a controllable degree. However, a total length of the position sensor thereby resulted, which was distinctly larger than its measuring range.

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While the designs in the past were principally disseminated with Villary bands sticking out diagonally from the waveguide, which was enveloped by the detector

coil, on the basis of the high amplitude that could be achieved thereby, this has the drawback of a complex manufacturing process.

5 In the past, it was already common, to use the waveguide itself either with a solid cross-section, thus as a conductor, or also with a hollow cross-section, as a tube. When also using the waveguide as an electrical conductor, the pre-form was favored, because of a lack of a magnetic field generated by the electrical current in the interior of the tubular electrical conductor.

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III. Depiction of the invention

a) Technical task

15 It is the role of the existing invention to simplify a position sensor of this construction principal so that function is guaranteed with sufficient accuracy, despite clearly lower production costs.

b) Resolution of the task

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This task is resolved through the features of claims 1 and 8. Advantageous embodiments result from the subsidiary claims.

25 Despite expectations, it was determined that when using an electrically conductive waveguide, which simultaneously serves as an electrical conductor, with coaxial configuration of the detector coil directly on the electrical conductor and configuration of a corresponding shielding around the detector coil, in particular in the form of a flux guide component, the information signal sufficiently differentiates itself from the existing interfering signal, in particular if the shielding
30 surrounds the detector coil as tightly as possible.

In doing so, a current feed of the detector coil cannot be dispensed with, but rather this even possibly has a negative impact, and also compensation for the

changing temperature within the detector array can be dispensed with after actuation of the sensor.

Consequently, the detector coil is arranged in an end range coaxial to the
5 filamentary waveguide and – before or after – provided with shielding, in particular by means of a likewise cylindrical flux guide unit. The sensor is functional after attachment of the detector coil to a detector circuit – after suitable suspension of the waveguide.

10 The form and arrangement of the flux guide unit relative to the detector coil will be selected so that the magnetic flux path enabled by the flux guide component at least surrounds the windings of the coils of the entire detector coil in at least one layer, for example, the axial layer. Preferably, the detector coil will enclose the flux path without interruption.

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To that effect, the form of the flux conductor component can be variably constructed:

In a simple embodiment, a C-forming flux conductor component overlaps the
20 coaxial on the detector coil applied to the waveguide so that the C-portion is directed to the waveguide with its free ends of both sides of the coil at a small distance. Thereby, a magnetic circuit is completed out of the C-forming flux guide component and the corresponding portion of the waveguide through the small air gap between the waveguide and the flux guide component, which represents the
25 magnetic flux path, which is enabled by means of the flux guide component.

Although the bulk of the detector coil lies outside of this magnetic circuit, the signal quality of the electrical signal delivered from the detector coil is thereby already strongly enhanced.

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The result is additionally improved in that the detector coil is wrapped in always increasing measure by the magnetic flux path, for example through the location of

two opposing C-shaped flux guide components or even more such C-shaped flux guide components distributed over the length of the waveguide.

In the ideal case, a correspondingly formed flux guide body encloses the detector
5 coil – except for the required inlets and outlets – completely as possible, and will thus normally consist of two complementary molds.

Even so, instead of and/or supplementary to the previously named measures, an improvement of the information signal relative to the interfering signal can be
10 achieved, if electrical return necessary for the position sensor is arranged coaxially around the detector coil, at least in the area of the detector coil, in particular especially tubular and preferably extensively enclosed, in any case.

This effect especially occurs when the material is not only electrically conductive,
15 but rather is also magnetically shielded and thus exhibits a permeability of $\mu > 1$.

c) Exemplary embodiment

Embodiments in accordance with the invention are more closely described with
20 examples in the following. Displayed are:

Fig. 1: A schematic diagram of the position sensor according to the invention,

Fig. 2: A cross-section through the waveguide 3,

25 Fig. 3 – 6: Additional designs of the flux guide unit.

Fig. 1 shows the entire position sensor, consisting of the waveguide 3 proceeding in measurement direction and on its detector assembly 105, as well as with the detector circuit 50 connected with the detector assembly 105.

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The detector circuit 50 can be arranged locally separated from the waveguide unit, and must be connected with detector coil 5 solely through two electrical conductors.

Without making contact, the position sensor measures the position of the moveable position magnets 28 in the measurement direction 10 along the waveguide unit relative to the sensor head of the waveguide 3, or up to the detector coil 5.

- 5 At least in sections, the waveguide 3 exhibits a solid cross-section of preferably circular external contour, in particular over its entire length, as shown in Fig. 2.

For example, in its progression, the waveguide 3 is accommodated in a support tube 4, which for instance possesses a clearly larger interior diameter as the
10 external diameter of the waveguide 3, and in which the waveguide 3 is coaxially positioned through the arrangement of a hose forming spacer 2 made of electrically non-conductive and non-magnetic material, more specifically a plastic material that is arranged coaxially around the waveguide 3 and with the support tube 4.

- 15 The free end of the waveguide 3 facing away from the detector head and thus the detector coil 5 is accommodated in a special dampening arrangement.

The detector coil 5 is arranged coaxial to the waveguide 3, but does not touch it, so that a spacer sleeve is positioned out of non-guide material in between.

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In the detector coil 5, the coils can be arranged in layers diagonally to the longitudinal direction 10, or also – in the construction of the detector coil 5 as a toroid coil – in layers along the longitudinal direction 10.

- 25 The waveguide 3 can only exit the detector coil 5 on a front side, as depicted in Fig. 1a, or completely penetrate the detector coil in the longitudinal direction, as depicted in Fig. 1b.

Independent thereof, the flux guide unit 30 only exhibits one or two opposing frontal
30 openings 5a, 5a' for the entry and, if necessary, the exit of the waveguide 3 and possible its insulating sleeve in respect to the detector coil 5, and in addition, at least one opening 5b for the passage of electrical connections from the detector coil

5 to the evaluation circuit 50.

In doing so, the flux guide unit 30 – as depicted in Fig. 1a – can consist of two half-
5 shells with junction planes parallel to the longitudinal direction 10 or also from a cup-shaped housing with frontal cover plate, as depicted in Fig. 1b.

Even a design made of two shell-shaped flux guide units 30c oriented with the open
sides against each other is possible, as depicted in Fig. 6 in the longitudinal section
10 and in a frontal view, in which the waveguide passes through the shell-shaped parts
30c through central waveguide openings 5a or 5a' into the otherwise closed
bottoms of the shell-shaped parts, while the electrical connections of the coil 5
leave the interior of the flux guide unit through at least one opening that cannot be
indicated here, preferably on the plane of contact of both shell-shaped parts 30c.

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In opposition to the previously described variants, in which the flux guide unit 30
completely encloses the detector coil 5 and the waveguide 3 as far as possible,
except for the passage openings for electrical connections, Fig. 3 – 5 in each case
show solutions in side and frontal views, in which the flux guide unit consists of one
20 or more C-shaped flux guide components 30a or 20b, which consequently do not
completely enclose the detector coil 5.

In the simplest solution according to Fig. 3, such a C-shaped flux guide component
30a, is arranged with its connecting longitudinal shank in the longitudinal direction
25 10, or parallel to the waveguide 3, so that both free ends of the C-part 30a are
oriented towards both sides of the frontal ends of the detector coil 5 against the
waveguide 3 and the C-shaped flux guide component 30a.

According to Fig. 4, two such C-parts 30a are correspondingly arranged on sides of
30 the waveguide 3, positioned in opposition each other, so that the entire detector coil
5 lies within the flux guidance component 30, but is not completely enclosed tightly
by it.

Through an increasing number of such C-parts 30a distributed over the length, for example, three C-parts 30a as depicted in Fig. 5, or a higher number of C-parts, the ranges of coverage of the detector coil 5 that is not covered by flux guide components become smaller and thereby the quality of the signal delivered by the
 5 detector coil becomes increasingly better.

Fig. 4c shows a modification of two C-shaped flux guide components 30b, which in this case are not arranged in each case on one of both sides of the waveguide, but rather are both threaded on the waveguide 3 by means waveguide openings 5a
 10 located in the connecting shanks of the C-parts 30b, while the free ending shanks of the flux guide component are positioned opposing each other and should mutually contact one another.

In the side view according to Fig. 4d, this solution is to be recognized that the
 15 detector coil 5 can be wound up in the H-shaped coil base plate 1 in the side view or also in the cross-section, instead of the base plate free, self-supporting detector coils 5 represented in the other drawings.

In the perspective view on the two opposing pages, Fig. 4c shows the sides of such
 20 a detector coil 5 not covered by the flux guide body, from which the corresponding connections for the detector coil 5 can be lead through.

In addition, Fig. 1c shows a solution, in which the likewise coaxial detector coil 5 arranged on the waveguide 3 is not surrounded by a flux guide unit but rather by a
 25 coaxial, tubular, electrical return positioned around the detector coil 5. This effect especially occurs when its material is not only electrically conductive, but rather is also magnetically shielded and thus exhibits a permeability of $\mu > 1$.

Also, magnetic fields impacting the detector coil 5 from outside are kept out by this
 30 means.

Even a combination of both possibilities is possible, or the arrangement of a flux guide unit in addition to a coaxial return 6 with the described characteristics.

DEVICE COMMENT LIST

5		
	1	Base plate
	2	Support hose
	3	Waveguide
	4	Support tube
10	5	Detector coil
	5a, 5a'	Waveguide opening
	5b	Connection opening
	6	Return
	7	Damping arrangement
15	10	Longitudinal direction
	28	Position magnet
	30	Flux connecting unit
	30a	C-shaped flux guide component
	30b	C-shaped flux guide component
20	30c	Shell-shaped flux guide components
	50	Evaluation circuit
	105	Detector arrangement